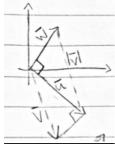
Exercise for chapter 7 – solution

<u>1.</u> ..

a.
$$proj_{\overline{w}}\overline{v} = \frac{\overline{v}^T \overline{w}}{|\overline{w}|^2}\overline{w} = \begin{bmatrix} 0\\ -1\\ 1 \end{bmatrix}$$

b. $proj_{\overline{v}}\overline{w} = \frac{\overline{w}^T \overline{v}}{|\overline{v}|^2}\overline{v} = \frac{-4}{11} \begin{bmatrix} -1\\ 1\\ 3 \end{bmatrix}$

<u>2.</u> Let $\bar{v} = \bar{u} - \bar{w}$.



Pythagorean theorem: $|\bar{u}|^2 + |\bar{w}|^2 = |\bar{v}|^2 = |\bar{u} - \bar{w}|^2$. This gives us: $\bar{u}^T \bar{u} + \bar{w}^T \bar{w} = (\bar{u} - \bar{w})^T (\bar{u} - \bar{w}) = (\bar{u}^T - \bar{w}^T)(\bar{u} - \bar{w}) = \bar{u}^T \bar{u} - \bar{u}^T \bar{w} - \bar{w}^T \bar{u} + \bar{w}^T \bar{w}$ We can cancel similar terms and get: $-\bar{u}^T \bar{w} - \bar{w}^T \bar{u} = 0$ But we know that $\bar{u}^T \bar{w} = \bar{w}^T \bar{u}$ (this is a scalar) So $2\bar{w}^T \bar{u} = 0$ and therefore $\bar{w}^T \bar{u} = 0$

$$\frac{3.}{\bar{x}} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix}, \ \bar{x}^T A \bar{x} = ?$$

$$A \bar{x} \text{ is a nx1 vector and therefore } \bar{x}^T A \bar{x} \text{ is a scalar.}$$

$$\bar{x}^T A \bar{x} = \sum_{i=1}^n x_i \sum_{j=1}^n a_{ij} x_j = \sum_{i=1}^n \sum_{j=1}^n x_i a_{ij} x_j$$

<u>4</u>. $\bar{x} \in \text{ker}(A)$ means that $A\bar{x} = \bar{0}$. From matrix multiplication we know that this means that every row of A multiplied by \bar{x} equal 0. Meaning that \bar{x} is orthogonal to the all the rows of A. rowsp(A) is the space spanned by all the rows of A. so every vector $\bar{a} \in \text{rowsp}(A)$ is just a linear combination of the rows of A. therefore, \bar{x} is orthogonal to any vector $\bar{a} \in \text{rowsp}(A)$

$$\underline{5.} \ \bar{u} = \begin{bmatrix} 1\\0\\3\\2 \end{bmatrix}, \bar{v} = \begin{bmatrix} 4\\1\\0\\1 \end{bmatrix}$$

$$|<\bar{u}, \bar{v} > | = 6$$

$$||\bar{u}|| = \sqrt{14}, ||\bar{v}|| = \sqrt{18}$$
And indeed
$$6 < \sqrt{14} * \sqrt{18} = 15.87$$

<u>6.</u>

<u>6.1.</u> Just show: $\overline{v_j}^T \overline{v_i} \begin{cases} = 0 \text{ if } i \neq j \\ > 0 \text{ if } i = j \end{cases}$

<u>6.2</u>. we are looking for 3 scalars c_1, c_2, c_3 that will satisfy: $\overline{u} = c_1 \overline{v}_1 + c_2 \overline{v}_2 + c_3 \overline{v}_3$

We will get 3 equations:

$$x = c_1 + c_2 + 5c_3$$

$$y = c_1 - 3c_2 - c_3$$

$$z = c_1 + 2c_2 - 4c_3$$

And we will get $c_1 = \frac{1}{3}(x + y + z)$, $c_2 = \frac{1}{14}(x - 3y + 2z)$, $c_3 = \frac{1}{42}(5x - y - 4z)$ <u>6.3</u>. $c_1 = 3, c_2 = -4, c_3 = 1$

<u>7.</u> *S*={v1,v2,...,vk} vectors in ℝn

<u>7.1.</u> Consider the linear combination

 $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k = \mathbf{0}.$

Our goal is to show that $c_1 = c_2 = \cdots = c_k = 0$.

We compute the dot product of \mathbf{v}_i and the above linear combination for each i = 1, 2, ..., k:

 $0 = \mathbf{v}_i \cdot \mathbf{0}$ = $\mathbf{v}_i \cdot (c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_k \mathbf{v}_k)$ = $c_1 \mathbf{v}_i \cdot \mathbf{v}_1 + c_2 \mathbf{v}_i \cdot \mathbf{v}_2 + \dots + c_k \mathbf{v}_i \cdot \mathbf{v}_k.$

As *S* is an orthogonal set, we have $\mathbf{v}_i \cdot \mathbf{v}_j = 0$ if $i \neq j$.

Hence all terms but the *i*-th one are zero, and thus we have

 $0 = c_i \mathbf{v}_i \cdot \mathbf{v}_i = c_i \|\mathbf{v}_i\|^2.$

Since \mathbf{v}_i is a nonzero vector, its length $||\mathbf{v}_i||$ is nonzero. It follows that $c_i = 0$.

As this computation holds for every i = 1, 2, ..., k, we conclude that $c_1 = c_2 = \cdots = c_k = 0$. Hence the set *S* is linearly independent.

<u>7.2.</u>

Suppose that k = n. Then by part (a), the set *S* consists of *n* linearly independent vectors in the dimension *n* vector space \mathbb{R}^n .

Thus, *S* is also a spanning set of \mathbb{R}^n , and hence *S* is a basis for \mathbb{R}^n .

8. From Schaum (example 7.10)

EXAMPLE 7.10 Apply the Gram–Schmidt orthogonalization process to find an orthogonal basis and then an orthonormal basis for the subspace U of \mathbf{R}^4 spanned by

$$v_1 = (1, 1, 1, 1),$$
 $v_2 = (1, 2, 4, 5),$ $v_3 = (1, -3, -4, -2)$

- (1) First set $w_1 = v_1 = (1, 1, 1, 1)$.
- (2) Compute

$$v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = v_2 - \frac{12}{4} w_1 = (-2, -1, 1, 2)$$

Set
$$w_2 = (-2, -1, 1, 2)$$
.

(3) Compute

$$v_3 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 = v_3 - \frac{(-8)}{4} w_1 - \frac{(-7)}{10} w_2 = \left(\frac{8}{5}, -\frac{17}{10}, -\frac{13}{10}, \frac{7}{5}\right)$$

Clear fractions to obtain $w_3 = (-6, -17, -13, 14)$.

Thus, w_1, w_2, w_3 form an orthogonal basis for U. Normalize these vectors to obtain an orthonormal basis $\{u_1, u_2, u_3\}$ of U. We have $||w_1||^2 = 4$, $||w_2||^2 = 10$, $||w_3||^2 = 910$, so

$$u_1 = \frac{1}{2}(1, 1, 1, 1),$$
 $u_2 = \frac{1}{\sqrt{10}}(-2, -1, 1, 2),$ $u_3 = \frac{1}{\sqrt{910}}(16, -17, -13, 14)$

<u>9.</u> Assume that Q and W are orthogonal matrices. That means that $Q^T Q = I$ and $W^T W = I$. Now let's calculate $(QW)^T QW = W^T Q^T QW = W^T IW = W^T W = I$. Which means that QW is an orthogonal matrix.

<u>11.</u>

additivity:

Suppose $u, v, w \in V$. Then

- homogeneity (scalar multiplication): show by yourselves.

12.
$$\|t \cdot \vec{v}\|^2 = (t\vec{v}, t\vec{v}) = t^2(\vec{v}, \vec{v}) = t^2 \|\vec{v}\|^2$$

 $\langle u,$